

A diagram showing a white rounded rectangle representing an environment. Inside the rectangle, at the top, is a green oval labeled "System (S)". Below the oval, the text "Environment (B)" is written in black.

System (S)

Environment (B)

# Open Quantum Systems in Quantum Computing

---

Xiantao Li  
Penn State University  
xli@math.psu.edu

## Why Open Quantum Systems?

- Quantum systems in reality are interacting with an environment (bath)  
⇒ open quantum systems
- These interactions have a deep impact on the system dynamics.
  - Quantum decoherence (Echo dynamics, Girin et al. Phys. Rep. 2006)
  - Gate error and error mitigation (Temme et al. PRL 2017)
- The study of open quantum systems starts with the combined system.
- The combined system usually has large dimension and is difficult to prepare and simulate directly.
- The theory of open quantum system attempts to identify models that implicitly incorporates the effect of the bath (Breuer & Petruccione).

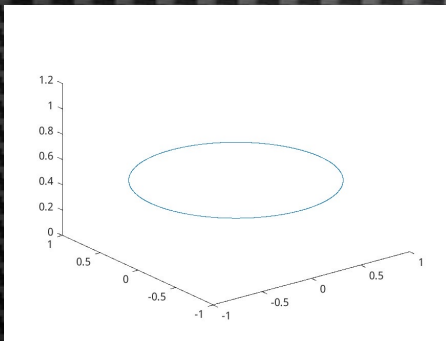
## Close quantum dynamics

- $H_S = -\frac{1}{20} \sigma_Z$
- $|\psi(0)\rangle = \frac{\sqrt{3}}{2} e^{-\frac{i\pi}{4}} |0\rangle + \frac{1}{2} e^{\frac{i\pi}{4}} |1\rangle$
- $x(t) = \langle \psi(t) | \sigma_x | \psi(t) \rangle, y(t) \dots$

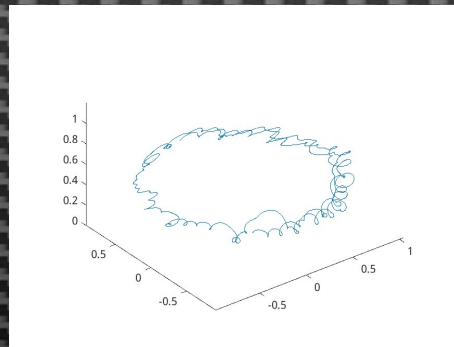
## With environment noise

(Gaspard-Nagaoka, JCP 1999)

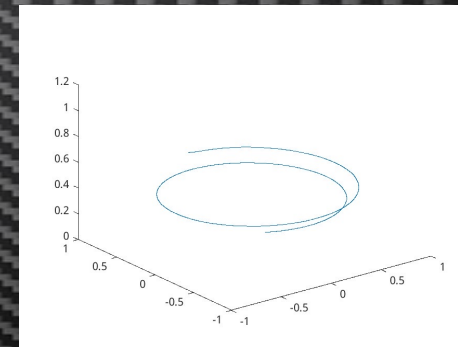
- **Boson bath**
- **Gaussian noise**
- **Coupling constant  $\lambda = 0.1$**



Time-dependent  
Schrödinger



Stochastic  
Schrödinger



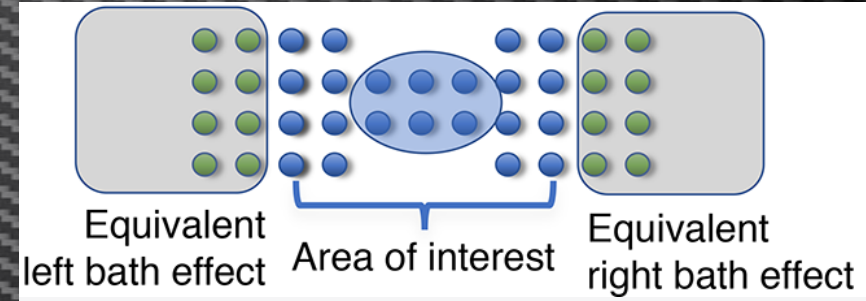
Quantum Master Eq., or  
Expectation from SSE



- Quantum optimal systems
  - Quantum electron dynamics (QED)
  - Photodetection
- Echo dynamics in NMR
- Cosmological system
  - Shandera et al 2018 Phys. Rev. D

## Electron transport

- The quantum device is connected to leads with different potential



- NEGF from Lindblad (Arrigoni et al PRL 2013).
- Stochastic TDDFT (Di Ventra-D'Agosta, PRL 2007)

- Markovian dynamics from the combined quantum system
- Quantum algorithms
  - Time-marching schemes
  - First-order scheme
  - Higher order approximation in the Kraus form
- Non-Markovian dynamics
  - Stochastic unravelling of non-Markovian dynamics
  - Markovian embedding of the memory
  - Generalized quantum master equation
  - Quantum algorithms

- **Total Hamiltonian:**  $H = H_S \otimes I_B + I_S \otimes H_B + \lambda H_I$
- **Liouville van Neumann equation**

$$\frac{d}{dt} \rho_{tot} = -i[H_{tot}, \rho_{tot}] \Rightarrow \rho_{tot}(t) = U_{tot}(t) \rho_{tot}(0) U_{tot}(t)^\dagger$$

- **Unitary evolution:**  $U_{tot}(t) = \exp(-itH_{tot})$ .
- $\rho_{tot}(0) = \rho_S(0) \otimes \rho_B(0), \rho_B(0) \propto \exp(-\beta H_B)$
- **System density-operator:**  $\rho_S(t) = \text{tr}_B(\rho_{tot}(t))$ .
- **The Kraus form** (Lidar et al 2001 Chem Phys.)

$$\rho_S(t) = \sum_j A_j(t) \rho_S(0) A_j(t)^\dagger$$

$$\langle m | A_j(t) | n \rangle = \langle m | \langle \mu | U_{tot}(t) | \nu \rangle | n \rangle, i = (\mu, \nu).$$

# Markovian dynamics

- **Interaction picture:**  $\rho_I(t) = U(t)^\dagger \rho(t) U(t)$   
 $U(t) = \exp -it(H_S \otimes I_B + I_S \otimes H_B)$
- **LvN in the interaction picture**  
$$\frac{d}{dt} \rho_I = -i\lambda [H_I(t), \rho_I(t)].$$
- **For example,**  $H_I(t) = S(t) \otimes B(t)$ .
- $\rho_I(t) = \rho_I(0) - i\lambda \int_0^t [H_I(t'), \rho_I(t')] dt'$
- $\frac{d}{dt} \rho_I = -\lambda^2 \int_0^t [H_I(t), H_I(t'), \rho_I(t')] dt'$
- **Assume weak coupling**  $\lambda \ll 1$   
$$\rho_I(t) = \rho_{S,I}(t) \otimes \rho_B + O(\lambda)$$
- **In addition, assume that**  $\langle B(t), B(t') \rangle \approx \delta(t - t')$ .
- **Then**  $\frac{d}{dt} \rho_{S,I} = -\lambda^2 c[S, S, \rho_{S,I}(t)]$
- **This is a Lindblad equation in the interaction picture. (Cao-Lu J. Math Phys)**

# From Lindblad $\longleftrightarrow$ Kraus?

- Markovian + CPTP  $\Rightarrow$  Lindblad-Gorini-Kossakowski-Sudarshan equation

$$\frac{d}{dt}\rho = -i[H_S, \rho] + \sum_j L_j \rho L_j^\dagger - \frac{1}{2} \{L_j^\dagger L_j, \rho\}$$

- Lindblad equation  $\Rightarrow$  Channel representations?
- Let's try the Euler's method
- Time steps:  $t_0, t_1, \dots, t_N = T; t_n = n\Delta t.$

- Euler:  $\rho_{n+1} = \rho_n + \Delta t G \rho_n + \Delta t \rho_n G^\dagger + \Delta t \sum_j L_j \rho_n L_j^\dagger$   
 $G = -iH - \frac{1}{2} \sum_j L_j^\dagger L_j$

- Kraus form:

$$\rho_{n+1} = (I + \Delta t G) \rho_n (I + \Delta t G)^\dagger + \Delta t \sum_j L_j \rho_n L_j^\dagger + O(\Delta t^2)$$

- $A_0 = I + \Delta t(-iH + G)$
- $A_j = \sqrt{\Delta t} L_j$



# Why quantum algorithms

- Classical computation for Lindblad has a complexity that is polynomial in the dimension  $N$ .
- For example, it involves matrix vector multiplication.
- Quantum algorithms may have complexity  $\log N \Rightarrow$  exponential speed
- Existing methods
  - Natural representation (Schlimgen et al PRR 2022)
  - Stinespring form (Wang et al, using Ham-generated unitary, PRL 2013)
  - Kraus form
- We will consider algorithms with high accuracy and complexity estimates.

# Time-marching schemes

- Lindblad equation:  $\frac{d}{dt}\rho = \mathcal{L}\rho$
- One-step approximation:  $e^{\Delta t\mathcal{L}}\rho \approx \mathcal{E}_{\Delta t}\rho$
- Global approximation:  $e^{T\mathcal{L}}\rho \approx \mathcal{E}_{\frac{T}{\Delta t}}^{\Delta t}\rho$
- Stinespring form.  
$$\rho(t + \Delta t) = e^{\Delta t\mathcal{L}}\rho \approx \text{tr}_A(U|0\rangle\langle 0| \otimes \rho(t)U^\dagger)$$
- Only need to specify the first col of  $U$ .
- For example.  $U = \exp -i\sqrt{\Delta t}J$ . (Cleve-Wang 2017)
- Global error  $O(T\Delta t)$ .
- Complexity  $O\left(\frac{T^2}{\epsilon}\right)$ .
- Improved method (T. Li and Childs 2017):  $O\left(\frac{T^{\frac{3}{2}}}{\epsilon^{\frac{1}{2}}}\right)$ .
- Nearly optimal complexity  $O(m^2q^2T \log \frac{1}{\epsilon})$  (Cleve-Wang 2017  $\mathcal{L}$  expressed as Paulis)

$$J = \begin{bmatrix} \sqrt{\Delta t}H_S & L_1^\dagger & L_2^\dagger & \cdots & L_m^\dagger \\ L_1 \\ L_2 \\ \vdots \\ L_m \end{bmatrix}$$

- How to find a higher-order Kraus form?
- A direct time discretization  $\not\Rightarrow$  CPTP map
- A structure-preserving method (Cao-Lu 2021)
- Decompose a Lindbladian:  $\mathcal{L} = \mathcal{L}_D + \mathcal{L}_J$
- $\mathcal{L}_D = \left[ -iH - \frac{1}{2} \sum_{j=1}^m L_j^\dagger L_j, \cdot \right]$ ;  $\mathcal{L}_J \rho = \sum_{j=1}^m L_j \rho L_j^\dagger$

## Duhamel's principle

- $\rho(t) = e^{t\mathcal{L}_D} \rho(0) + \int_0^t e^{(t-t_1)\mathcal{L}_D} \mathcal{L}_J \rho(t_1) dt_1$
- $\rho(t) = e^{t\mathcal{L}_D} \rho(0) + \int_0^t e^{(t-t_1)\mathcal{L}_D} \mathcal{L}_J e^{t_1\mathcal{L}_D} \rho(0) dt_1 + O(t^2)$

- Repeat for the formula K times

$$\rho(t) = e^{t\mathcal{L}_D} \rho(0) + \sum_{k=1}^K \int e^{(t-t_k)\mathcal{L}_D} \mathcal{L}_J e^{(t_k-t_{k-1})\mathcal{L}_D} \dots \rho(0) dt_1 \dots dt_k$$

$$+ O\left(\frac{(2\|L\|t)^{K+1}}{(K+1)!}\right)$$

## Observations

- $e^{t\mathcal{L}_D} \rho(0) = D\rho(0)D^\dagger$ ,  $D = \exp -t(iH + \frac{1}{2}\sum_{j=1}^m L_j^\dagger L_j)$
- It is a CP map in the Kraus form.
- $\mathcal{L}_J \rho = \sum_{j=1}^m L_j \rho L_j^\dagger$  is also CP in the Kraus form
- A composition of CP maps is CP
- Overall the solution is expressed in a Kraus form.

# Approximating the integrals

- The integrals are treated with Gaussian quadrature

- Gaussian quadrature  $(s_1, s_2, \dots, s_q), (w_1, w_2, \dots, w_q)$

- $\int_0^1 f(t) dt = \sum_{j=1}^q w_j f(s_j) + O\left(\frac{q \|f^{2q}\|}{(2q)! 2^{4q-1}}\right)$ .

- $\int e^{(t-t_k)\mathcal{L}_D} \mathcal{L}_J e^{(t_k-t_{k-1})\mathcal{L}_D} \dots \rho(0) dt_1 \dots dt_k$   
 $\approx \sum_{j_1=1}^q \sum_{j_2=1}^q \dots \sum_{j_k=1}^q w_{j_k}, w_{(j_k, j_{k-1})}, \dots, w_{(j_k, \dots, j_1)} F_k(s_{j_k}, s_{(j_k, j_{k-1})}, \dots, s_{(j_k, \dots, j_1)}) + O\left(\frac{\|G\|^{2q} 2^{2k} t^{2q+k}}{(k-1)! (2q)!}\right)$

- The sum of the coefficients  $\sum_{j_1} \sum_{j_2} \dots \sum_{j_k} w_{j_k}, w_{(j_k, j_{k-1})}, \dots, w_{(j_k, \dots, j_1)} = \frac{t^k}{(k+1)!}$

- Truncation:  $K, q = \frac{\log 1/\epsilon}{\log \log 1/\epsilon}$ .

## Implementing the Kraus forms

- A general CPTP map in a Kraus form

$$\mathcal{E}\rho = A_0\rho A_0^\dagger + \sum_{j=1}^M A_j\rho A_j^\dagger.$$

- **Block-encode**  $A_j$ :  $A_j \approx s_j(\langle 0| \otimes I)U_j(|0\rangle \otimes I)$
- $|\mu\rangle \propto \sum_j s_j|j\rangle$ .
- $W = \sum_j |j\rangle\langle j| \otimes U_j|\mu\rangle\langle 0| \otimes I$ .
- $\sum_j |j\rangle\langle j| A_j|\psi\rangle \approx I \otimes \langle 0| \otimes I \sum_j |j\rangle\langle j| \otimes U_j|\mu\rangle\langle 0| |\psi\rangle$
- $|\rho_{new}\rangle = (A_0|\psi\rangle, \dots, A_j|\psi\rangle, \dots)$
- $\mathcal{E}\rho = \text{tr}_A(|\rho_{new}\rangle\langle\rho_{new}|)$

## Main theorems

- Norm of the Lindbladian:  $\|\mathcal{L}\|_{be} = \alpha_0 + \sum_{j=1}^m \alpha_j^2$ .
- Theorem (Li and Wang 2023). Suppose that we have the block encodings of  $H_S$  and  $L_j, j = 1, 2, \dots, m$ . For all  $t, \epsilon > 0$ , there is a quantum algorithm that yields an approximate density operator  $\rho(t) = e^{t\mathcal{L}}\rho(0)$ , with error within  $\epsilon$  using  $O(t\|\mathcal{L}\|_{be} \text{polylog}\frac{t}{\epsilon})$  queries and  $O(tm\|\mathcal{L}\|_{be} \text{polylog}\frac{t}{\epsilon})$  additional 1- and 2-qubit gates.

- Why non-Markovian?
- When there is no scale separation, non-Markovian properties emerge.
  - Divergence from standard properties [Gröblacher, non-Ohmic spectral density, 2015].
  - Measuring non-Markovianity [Breuer 2009].
  - Modeling a non-Markovian quantum dynamics
  - Controlling a non-Markovian dynamics
- There is a backflow of information.
- There is no universal form for the QME.
- It is difficult to preserve the CP property.
- The form of the equations depends heavily on the bath properties
- Our approach: Stochastic unravelling.



# The connection with SSE

- A stochastic Schrödinger equation is a more intuitive description
- Stochastic Schrödinger

$$id\psi = (H_S - \frac{i\lambda^2}{2} \sum_{j=1}^M L_j^\dagger L_j) \psi dt + \lambda \sum_{j=1}^M L_j \psi dW_j$$

- The equation is written in the Ito form.
- $dW_j$ : complex-valued white noise (multiplicative)
- SDE:  $dz_t = a(z_t)dt + b(z_t) \circ dW_t$  (Stratonovich)
- Then  $z_t = e^{D_t} z_0$ , (Stochastic flow Kunita 1994)

$$D_t = tX_0 + W_t X_1 + \frac{1}{2} \left( \int_0^t s dW_s - \int_0^t W_s ds \right) [X_0, X_1] + \dots$$

$$X_0 = a \cdot \nabla_{z_0}, X_1 = b \cdot \nabla_{z_0}.$$

- Application to SSE (Li and Li PRE 2020).

$$|\psi(t)\rangle = \exp \left( -itH - \frac{t}{2} (L^\dagger + L)L + LW_t + K_{(0,1)} \left( \frac{1}{2} [L^\dagger, L]L + i[H, L] \right) + \dots \right) |\psi(0)\rangle$$

- The covariance  $\rho(t) = E[|\psi(t)\rangle\langle\psi(t)|]$  satisfies Lindblad Eq.
- Can we use SSE to derive non-Markovian dynamics?

# Stochastic Schrödinger Equation

- Schrödinger equation  $i\partial_t\Psi = H\Psi$ .
- A complete basis in  $\mathcal{H}_B$ .  $H_B|n\rangle = \varepsilon_n|n\rangle$ ,  $|n\rangle = \chi_n(r_B)$ .
- Expand  $\Psi = \sum_n \varphi_n(r_S, t)\chi_n(r_B)$ .
- An infinite set of equations for  $\varphi_n(\cdot, t)$  with
- Assume that  $H = H_S \otimes I_B + I_S \otimes H_B + \lambda S \otimes B$ ,  $0 < \lambda \ll 1$ .
- Using perturbations: ( $\phi$  as a realization of  $\varphi_n$ ) [Gaspard-Nagaoka 1999]

$$i\partial_t\phi = H_S\phi - i\lambda^2 S^\dagger \int_0^t C(\tau) e^{-iH_S\tau} S\phi(t-\tau) d\tau - i\lambda S\eta(t)$$
$$C(t) = \text{tr} \left( \rho_B^{eq} B(t)B(0) \right).$$

- The correlation is related to the spectral density
- This NM SSE does not have an exact QME.

- It is typically expensive to solve the non-Markovian SSE directly
- We start with the SSE:

$$i\partial_t\phi = H_S\phi - i\lambda^2 S^\dagger \int_0^t C(\tau)e^{-i\tau H_S} S\phi(t-\tau)d\tau - i\lambda S\eta(t)$$

- Approximating  $\eta(t)$  by a complex OU process (Risken)
  - $i\dot{\zeta} = -\alpha\zeta + \gamma\dot{W}(t)$ .
  - If  $\gamma^2 = 2\text{Im}[\alpha]$ ,  $c(t, t') = \langle \zeta(t)^*\zeta(t') \rangle = e^{-i\alpha^*(t-t')}$ ,  $t \geq t'$ .
  - Idea: Use  $c(t, t')$  and  $\zeta(t)$  as building blocks to approximate  $C(t)$  and  $\eta(t)$
- Approximation by exponentials:
  - Set  $C(t) = \theta^2 e^{-i\alpha^*t}$ ,  $\eta(t) = \theta\zeta(t)$ .  
 $\Rightarrow \langle \eta(t)^*\eta(s) \rangle = C(t-s)$ .
  - Define  $\chi = \frac{\lambda}{\theta} \int_0^t C(\tau)e^{-i\tau H_S} S\phi(t-\tau)d\tau$ . An auxiliary orbital.
  - Equation for  $\chi$ :  $i\partial_t\chi = (H_S + \alpha^*)\chi + i\lambda\theta S\phi$ .

# Approximating the BCF

- An extended stochastic system

$$i\partial_t\phi = H_S\phi - i\lambda\theta S^\dagger\chi + \lambda\theta S\phi\zeta(t)$$

$$i\partial_t\chi = (H_S + \alpha^*)\chi + i\lambda\theta S\phi.$$

$$i\dot{\zeta} = -\alpha\zeta + \gamma\dot{W}(t).$$

- Multiple exponential functions:

$$C(t) \approx \sum_k \theta_k^2 e^{i\alpha_k^* t}.$$

- The power spectrum

$$|G(\omega)|^2 \approx \sum_k \frac{2\theta_k^2 \nu_k}{(\omega + \mu_k)^2 + \nu_k^2}$$

- This is a sum of Lorentzians.

The non-Markovian dynamics is now embedded in an extended, but Markovian dynamics.

The computation is much more efficient.

Ritschel-Eisfeld 2014 JCP

$$\alpha(t) = \frac{1}{\pi} \int_0^\infty d\omega J(\omega) \left( \coth\left(\frac{\omega}{2T}\right) \cos(\omega t) - i \sin(\omega t) \right),$$

$$J_k(\omega) = \frac{1}{(\omega - \Omega_k)^2 + \gamma_k^2}.$$

$$J_{DL}(\omega) = 2\pi\lambda\omega \frac{\gamma}{\omega^2 + \gamma^2},$$

$$J_{ohm}(\omega) = \eta\omega e^{-\omega/\Lambda},$$

$$J_{vib}(\omega) = \frac{\sum \omega^2 J_{ohm}(\omega)}{(\omega - \tilde{g}(\omega))^2 + J_{ohm}^2(\omega)}$$

$$J_{bg}(\omega) = \sqrt{\frac{\pi S \omega}{2\pi\sigma}} e^{-[\ln(\omega/\omega_c)]^2 / 2\sigma^2}.$$

- Define an auxiliary orbital:  $\chi^{II} = i\phi(t)\zeta(t)$
- Keep up to  $\mathcal{O}(\lambda^2)$  terms,

$$\begin{aligned} i\partial_t\phi &= H_S\phi - i\lambda\theta S^\dagger\chi^I - i\lambda\theta S\chi^{II} \\ i\partial_t\chi^I &= (H_S + \alpha^*)\chi^I + i\lambda\theta S\phi. \\ i\partial_t\chi^{II} &= (H_S - \alpha)\chi^{II} + i\gamma\phi\dot{W}(t). \end{aligned}$$

- We obtain linear SDEs.
- $\mathcal{O}(\lambda^3)$  approximations,

$$\begin{aligned} i\partial_t\chi^I &= (H_S + \alpha^*)\chi^I + i\lambda\theta S\phi. \\ i\partial_t\chi^{II} &= (H_S - \alpha)\chi^{II} - i\lambda\theta S^\dagger\chi^{III} - i\lambda\theta S\chi^{IV} + i\gamma\phi\dot{W}(t). \\ i\partial_t\chi^{III} &= i\lambda\theta S\chi^{II} + (H_S + \alpha^* - \alpha)\chi^{III} + i\gamma\chi^I\dot{W}(t). \\ i\partial_t\chi^{IV} &= i\lambda\theta S^\dagger\chi^{II} + (H_S - 2\alpha)\chi^{IV} + 2i\gamma\chi^{II}\dot{W}(t). \end{aligned}$$

- Non-Markovian SSE

$$i \frac{d}{dt} \psi = H\psi - i\lambda^2 \sum_{\alpha, \beta=1}^M \int_0^t C_{\alpha, \beta}(\tau) S_{\alpha}^{\dagger} e^{-i\tau H} S_{\beta} \psi(t - \tau) d\tau$$

$$+ \lambda \sum_{\alpha=1}^M \eta_{\alpha}(t) S_{\alpha} \psi(t).$$

- Time correlation:  $E[\eta_{\alpha}(t)\eta_{\beta}(t')^{\dagger}] = C_{\alpha, \beta}(t - t')$ .
- Approx. BCF:  $C(t) \approx \sum_{j=1}^J \theta_j^2 |R_j\rangle\langle R_j| e^{-id_j t}$ .  $\text{Im}d_j \geq 0$ .
- Auxiliary wave function,  $\{\chi_{j, \beta}^I, \chi_{j, \beta}^{II}, \chi_{j, \beta}^{III}, \chi_{j, \beta}^{IV}\}$

# The generalized quantum master eqn (GQME)

- **Linearity**  $\Rightarrow$  closed form of the density-matrix equation.
- $\Gamma = E[|\Phi\rangle\langle\Phi|]$ .  $\Phi = [\phi \chi^I \chi^{II}]$ .  $\rho_S = E[|\phi\rangle\langle\phi|]$ .
- **Extended system:**  $i\partial_t \Phi = H\Phi + \sum_k V_k \phi \dot{W}(t)$ . **Unravelling of NM dynamics**
- **QME:**  $i\partial_t \Gamma = H\Gamma - \Gamma H^\dagger + \sum_k V_k \rho V_k^\dagger$ .
  - It is not exactly Lindblad.
  - It preserves the positivity.

- **The initial condition:**  $\Gamma(0) = \begin{bmatrix} \rho_S(0) & & & \\ & 0 & & \\ & & \rho_S(0) & \\ & & & 0 \\ & & & & \rho_S(0) \end{bmatrix}$ .

- **Density:**  $\rho_S(t) = Q\Gamma(t)Q^T$ , ( $Q = |0\rangle \otimes I$ ) is the first diagonal block.  
 $tr(\rho_S) = 1 + O(\lambda^3)$

- The Hamiltonian

- $H_0 = \begin{bmatrix} H_S & -i\lambda\theta_1 S^\dagger & \lambda c_1 S & -i\lambda\theta_2 S^\dagger & \lambda c_2 S & \dots \\ i\lambda\theta_1 S & H_S + \alpha_1^* & 0 & 0 & 0 & \dots \\ \lambda c_1 S^\dagger & 0 & H_S - \alpha_1 & 0 & 0 & \dots \\ i\lambda\theta_2 S & 0 & 0 & H_S + \alpha_2^* & 0 & \dots \\ \lambda c_2 S^\dagger & 0 & 0 & 0 & H_S - \alpha_2 & \dots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \ddots \end{bmatrix}$

- $H = I_A \otimes H_S + H_A \otimes I_S + i\lambda \sum_k D_k \otimes T_k + i\lambda \sum_k E_k \otimes T_k^\dagger$

- The space is enlarged to mimic the influence of the environment.



## The properties of the GQME

- Perturbation form:  $\partial_t \Gamma = \mathcal{L}_0 \Gamma + \lambda \mathcal{L}_1 \Gamma$

**Theorem:** The solution of the unperturbed GQME is bounded for all time:

$$\|\Gamma_0(t)\| \leq C \|\Gamma_0(0)\|, \forall t \geq 0.$$

The block of  $\Gamma(t)$ ,  $\tilde{\rho}(t)$  follows unitary evolution.

The trace is given by:  $\text{tr}(\Gamma_0(t)) = 2K + 1 + \sum_{1 \leq k \leq K} e^{-4\nu_k t}$ .

The trace of  $\Gamma(t)$  has the bound

$$\text{tr}(\Gamma(t)) = 2K + 1 + \sum_{1 \leq k \leq K} e^{-4\nu_k t} + O(\lambda^2).$$

The block of  $\Gamma(t)$ ,  $\tilde{\rho}(t)$ :  $\text{tr}(\tilde{\rho}(t)) = 1 + O(\lambda^3)$ .

- Model Error: From the system dynamics, one can apply an asymptotic analysis.

- $\rho_S(t) = \rho_S^{(0)}(t) + \lambda \rho_S^{(1)}(t) + \lambda^2 \rho_S^{(2)}(t) + O(\lambda^3).$

- The first order term disappears after the partial trace
- The second order term involves the BCF.

**Theorem (Li-Wang 2023).** Let  $\hat{\rho}_S(t)$  be the first diagonal block of  $\Gamma$ :  $\hat{\rho}_S = \langle 0 | \Gamma | 0 \rangle$ . Then

- $\left\| \hat{\rho}_S(t) - \left( \rho_S^{(0)}(t) + \lambda^2 \rho_S^{(2)}(t) \right) \right\| \leq C \lambda^3.$

- The GQME is consistent with the second order expansion.

## Simulating the non-Markovian dynamics

- Kraus form from an infinitesimal approximation:

$$M_{\Delta t} \rho = A_0 \rho A_0^\dagger + \sum_m A_m \rho A_m^\dagger$$

- $A_0 = I - i\Delta t H$

- $A_m = \sqrt{\Delta t} V_m$

- $\|M_{\Delta t} \rho - e^{\Delta t L}\|_\diamond \leq 5 \|L\|^2 \Delta t^2$ . But it can be improved to higher order.

Theorem (Li-Wang, CMP, 2023). Suppose that we are given the access to block encodings of  $H_S$  and  $S_m$ ,  $m \in [M]$ ,  $\lambda > 0$ ,  $d_k, k \in [K]$ , and  $\rho_S(0)$  that exists a quantum algorithm that produces  $\rho_S(t)$  s.t.  $\|\rho_S(t) - \langle 0| \otimes \Gamma(t) |0\rangle \otimes I\| < \epsilon$ . The algorithm uses  $O\left(t \text{polylog}\left(\frac{t}{\epsilon}\right) \text{poly}(M, K, \lambda)\right)$  queries to  $H_S$  and  $S_m$  and additional 1 and 2-qubit gates.

## Extensions of Lindblad simulations

- Multiple time scales
- Time-dependent Lindbladians

## Non-Markovian QME

- Time local Lindbladians
- Hierarchical equations of motions (HEOM)

## What can we use these simulators for?

- Reaching thermal state?
- Control of open quantum systems.
- Quantum error mitigation?
- Electron transport. (how to deal with the nonlinear potential?)

## References

- Li-Wang, Efficient Simulating Markovian open quantum systems using higher-order series expansion, ICALP, 2023.
- Li-Wang, Succinct Description and Efficient Simulation of Non-Markovian Open Quantum Systems Communications in Mathematical Physics, 2023.
- Li, On Markovian Embedding Procedures for the Non-Markovian Stochastic Schrodinger Equation, Physics Letters A, 2021.
- Cleve-Wang, Efficient Quantum Algorithms for Simulating Lindblad Evolution, ICALP 2017.
- Childs-Li, Efficient simulation of sparse Markovian quantum dynamics, quantum information and computation, 2017.
- Cao-Lu: Lindblad equation and its semiclassical limit of the Anderson-Holstein model. J. Math. Phys. 2017.